Hackaday

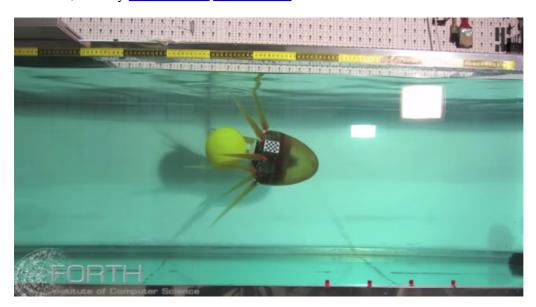
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Robotic Octopus to Take Over the Seas

October 3, 2014 By James Hobson 12 Comments



Much of robotics has been advanced by recreating animals movements – Why reinvent the wheel when nature got it right first? But have you seen many aquatic creatures movements re-imagined with mechanical linkages? The Foundation for Research and Technology-Hellas (FORTH) has recently <u>presented their robotic octopus</u> at the International Conference on Intelligent Robots and Systems.

The eight armed (or is it legged?) *roboctopus* was based on of a real octopus which have a really cool method of propulsion which allows them to move at speeds of up to 40km/h. The researchers in Greece created slim silicon arms to recreate this movement, allowing their robot to propel itself at speeds of around 10cm/s — after adding webs to the arms, they were able to almost double its top speed to 18cm/s, or one-half its body length per second.

The cool thing about the bot is that other marine wild-life seem relatively unperturbed by it, which could open up many possibilities in underwater research!

Between <u>robotic kangaroos</u>, <u>rats</u>, <u>red snappers</u> and <u>even elephants</u> we'll be able to have a robotic zoo in no time!

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[via TechPlus24]



Filed Under: robots hacks Tagged With: robotic animals, robotic octopus



Comments

1. Dax says:

October 3, 2014 at 4:04 pm

After a bit of unit conversion, it does 0.7 kph, which is rubbish compared to 40 kph.

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• *dsblackout* says:
October 3, 2014 at 5:05 pm

But amazing for a robotic imitation that can't *quite* imitate the original properly. Tentacles are a LITTLE bit hard to imitate in robots, what with the infinite degree of flexibility and all.

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2. NotArduino says:

October 3, 2014 at 4:39 pm

Yes, this will definitely take over the seas.

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3. OneShotWillie says:

October 3, 2014 at 6:17 pm

I, for one, welcome our new overlords...

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4. Hirudinea says:

October 3, 2014 at 7:16 pm

Greeks invented a robotic octopus? Did they eat it when they were done? Anyway it looks like it swims more like a jellyfish, why not forget the tentacles and just go for a full "cowl" or whatever the hell you call a jellyfish head.

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• Royell says:

October 4, 2014 at 9:37 pm

Bell*

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• *Lampros* says:

October 6, 2014 at 8:25 am

As a biologist, i couldn't disagree more: Jellyfish swim with contractions of the bell (as Royell very correctly remarked) or as others call it: hood. Cephalopods on the other side, display a much wider range of motion modes. The ones displayed here, are motions performed mainly by the tentacles (an organ homologous to the foot of a gastropod (snail). Other modes of motion involve the contraction of the mantle which might initially look like the motion of the jellyfish but is in fact a more involved and much faster mode of motion.

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5. Jerzee says:

October 3, 2014 at 11:43 pm

Being a swimmer and looking at the motion in the footage provided I wonder why they didn't incorporate a one-way water inlet valve. In strokes life the a portion of your forward motion is taken up by the recoil phase of the stroke, the same goes for the way the footage in this video shows its swim pattern. A simple oneway valve would reduce the drag caused by turbulance and resistance of the water refilling the expanding webbing of the tenticles. I would not be suprised if they could double their current speed and reduce energy consumption by including inlet valves.

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6. Thinkerer says:

October 4, 2014 at 7:56 am

Festo has jellyfish like this they bring to trade shows – the tentacles aren't independent but it's a charming display.

http://scienceblogs.com/zooillogix/2008/04/24/robotic-jellyfish-that-move-au/

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7. heatgap says:

October 4, 2014 at 8:19 am

Ok yeah I'm definitely getting a creepy vide from this.

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• heatgap says:

October 4, 2014 at 8:20 am

vibe*

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8. *Gerard* says:

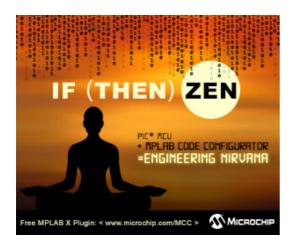
October 7, 2014 at 8:08 am

So remind me, what eats squid? Blue sharks eat squit https://www.youtube.com/watch?v=OlgsvnvcbC8

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